Abstract—Mobile Crowd Sensing (MCS) is a relatively new paradigm for collecting real-time and location-dependent urban sensing data. Given its applications, it is crucial to optimize the MCS process with the objective of maximizing the sensing quality and minimizing the sensing cost. While earlier studies mainly tackle this issue by designing different combinatorial optimization algorithms, there is a new trend to further optimize MCS by integrating learning techniques to extract knowledge, such as participants’ behavioral patterns or sensing data correlation. In this article, we perform an extensive literature review of learning-assisted optimization approaches in MCS. Specifically, from the perspective of the participant and the task, we organize the existing work into a conceptual framework, present different learning and optimization methods, and describe their evaluation. Furthermore, we discuss how different techniques can be combined to form a complete solution. In the end, we point out existing limitations which can inform and guide future research directions.

Index Terms—Mobile Crowd Sensing, Learning, Optimization.

1 INTRODUCTION

Coined by Howe and Robinson in [1], the idea of crowdsourcing has become an emerging distributed problem-solving paradigm by combining the power of both human computation and machine intelligence. Furthermore, the prevalence of mobile devices and the increasing smart sensing requirements in the city have led to an alternative or complementary approach for urban sensing, called Mobile Crowd Sensing (MCS) [2], [5]. MCS leverages the inherent mobility of mobile users (i.e., participants or workers), the sensors embedded in mobile phones and the existing communication infrastructures (Wi-Fi, 4G/5G networks) to collect and transfer urban sensing data. Compared to wireless sensor networks (WSN), which are based on specialized sensing infrastructures, MCS is less costly and can obtain a higher spatial-temporal coverage.

However, every coin has its two sides. Although with the above advantages and various MCS-enabled innovative applications [8], [9], [10], [11], [12], [13], the new sensing paradigm also encounters new challenges as “humans” act as sensors [14]. First, the sensing quality problem is more complex in MCS, because human sensors are quite complex and several human factors have to be taken into account. For example, it is uncertain to predict if the participants would accept the recommended sensing tasks or not. Even if they accept the task, factors such as reliability, user preference, expertise, and mobility pattern may significantly affect how they will complete these tasks (e.g., coverage and sensing quality). Second, participating in an MCS campaign incurs extra cost (e.g., energy consumption and data transferring cost) and concerns (e.g., location privacy leak) to the participants. Keeping the cost as low as possible is beneficial for motivating participants to contribute their data. In summary, with the objective of maximizing sensing quality and minimizing sensing cost control, it is crucial to optimize the entire lifecycle of MCS, and the number of relevant research works has continuously increased in recent years.

Earlier studies mainly tackle this issue from the perspective of designing different combinatorial optimization algorithms in participant selection or task assignment. With the rapid technical progress in learning-based artificial intelligence, we notice that it is now an emerging trend to integrate the learning techniques into the research problem of MCS optimization. On the one hand, a group of studies, such as [21], [22], [23], [25], [26], [27], focus on how to understand participation behavior, and then exploit the obtained knowledge to future optimize the MCS process (such as participant selection and task assignment). On the other hand, another category of works, such as [42], [43], [44], [48], [49], [50], leverage the correlation among sensing data (such as spatial-temporal correlation) or data inference techniques to optimize MCS in several aspects, such as reducing the cost in sensing data sampling and discovering truth through sensing results aggregation.

In recent years, there are several survey or tutorial papers in the MCS research community. Some [2], [4], [5] focus on the description of overall and general picture (e.g., lifecycles, research issues, and challenges) in MCS, and others such as [15], [16], [17], [18], [19] dive into specific research topics in MCS, including incentive mechanisms [15], [16], privacy preservation [17], [18], and energy saving [19]. However, to the best of our knowledge, there are no survey or tutorial papers summarizing how learning techniques are explored to assist the MCS optimization process. Therefore, this motivates the need for a compre-
hensive survey.

With the above motivation, we conduct a comprehensive survey of all publications related to learning-assisted MCS optimization via a paper selection process guided by a suggestion made in [3]. The main criteria for including a paper are: a) whether it describes a research problem in MCS or similar concepts (e.g., participatory sensing, mobile crowdsourcing, and spatial crowdsourcing), and b) does the article utilize learning techniques to optimize a certain aspect of MCS. We performed three types of literature searches before Nov 2017: a) Online digital libraries including ACM, IEEE Xplore, Springer Link, Wiley, Elsevier ScienceDirect, and Google Scholar. b) Main conference proceedings and journals in fields such as ubiquitous computing, mobile computing, and wireless sensor networks from January 2008 to Nov 2017. The specific conference proceedings and journals are on the top proceeding lists within the fields [67]. c) By searching the citations from included papers, we further discovered some additional relevant papers.

The contributions of this survey paper include:

1) We present a comprehensive survey of the literature using learning techniques to optimize the process of MCS, which is a hot topic in MCS research community but lacks survey or tutorial papers. To the best of our knowledge, this article is the first work summarizing MCS optimization techniques from a learning-assisted perspective.

2) We classify the relevant works from the perspective of both participants and tasks, with the objective of maximizing quality or minimizing cost. In addition to presenting each individual technique, we discuss how they are evaluated, analyze their relationships, and discuss how they can be combined to optimize MCS systems collaboratively.

3) We highlight the existing gaps for the state-of-the-art learning-assisted MCS optimization approaches and present some future research opportunities.

2 MCS AND ITS OPTIMIZATION

In this section, we present some basic background knowledge about MCS and its optimization. For more detailed understanding about MCS and its main research issues, interested readers can refer to other surveys and tutorials [2], [4], [5].

2.1 Preliminary of MCS

Compared to general crowdsourcing, MCS have two unique features. (1) Mobility-Relevant Features. Different from general crowdsourcing tasks, MCS requires the workers to complete sensing tasks in certain locations, because the sensing results are location-dependent (e.g., air quality, noise level, and traffic congestion status). (2) Sensing-Relevant features. Different from general crowdsourcing, MCS always targets at urban sensing tasks. First, the execution of sensors and localization modules introduces much more energy consumption into MCS than general crowdsourcing. Therefore, it is important to control the energy consumption of workers in the MCS systems. Second, many MCS tasks need to invoke phone-embedded sensors for task completion, but the set of sensors for each worker may be different as they hold various brands and models of smart devices.

Similar to the notion of participatory sensing [6] and human-centric computing [7], there are two key players in MCS, i.e., participants who collect and report sensing data through a mobile device, and task organizers who manage and coordinate the whole MCS process. The life-cycle of MCS can be divided into four stages: task creation, task assignment, task execution and data aggregation. The main functionality and research issues of each stage are briefly described as follows:

a) Task Creation: The MCS organizer creates an MCS task to be given to workers with the corresponding mobile applications. In this stage, the key research issue is how to reduce the time and the technical threshold of task creation [62], [63].

b) Task Assignment: After the organizer creates an MCS task, the next stage is task assignment, in which the MCS platform selects participants and assigns them with the different sensing tasks. The key research issue at this stage is how to optimize MCS taking into account a number of different factors, such as spatial coverage, incentive cost, energy consumption, and task completion time [29], [64].

c) Task Execution: Once the participants have received the assigned micro-sensing tasks, they can complete them within a predefined spatial-temporal scale (i.e., time duration and target region). This state includes sensing, computing, and data uploading. How to save energy consumption and protect users’ location and overall privacy are the core research challenges at this stage [18], [19].

d) Data Integration: This stage fuses the reported data from the crowd according to the requirements of task organizers. The key issue at this stage is how to infer missing data and provide a complete spatial-temporal picture of the target phenomenon (e.g., real-time air quality map of a city) [43], [45].

2.2 Two Aspects of MCS Optimization: Quality and Cost

For the optimization of MCS, the control of sensing quality and cost is a fundamental research problem. On the one hand, we want to maximize the sensing quality of an MCS task. The sensing quality metric can be diverse for different applications (e.g., spatial-temporal coverage, Quality-of-Information, mean error rate, etc.) [20]. On the other hand, we need to control the cost during the MCS process. The cost may include incentive rewards, energy consumption, data transferring expense, privacy leak, attention occupation, etc. [15], [16], [17], [18], [19].

However, the sensing quality maximization and sensing cost minimization are usually two opposing objectives. For example, to optimize the spatial-temporal coverage, we may need to recruit more participants, which will then lead to a higher total sensing cost. Therefore, how to achieve a good tradeoff between sensing quality and cost is a major research issue in MCS.

3 LEARNING-BASED MCS OPTIMIZATION: A CONCEPTUAL FRAMEWORK

In Fig 1, we present a conceptual framework for learning-based MCS optimization, which primarily consists of the following two phases.
Learning Phase: we can extract knowledge from both participants and tasks. In terms of participants, with various machine learning techniques (such as classification, clustering, and regression), we can form a better understanding towards both the individual or the community of the participants for several aspects, such as willingness, mobility pattern, sensing context, ability, and reputation. In terms of tasks, it analyzes and discovers the correlation between different types of sensing data and tasks.

Optimization Phase: we can leverage the extracted knowledge to optimize the MCS campaign in the following aspects:

1) Sensing quality control. MCS faces the challenge of low-quality or even erroneous data collection. For example, a smartphone may report inaccurate data samples when it is located in a bag or pocket [21], or a participant may report malicious sensing data for his own benefit [2]. With this in mind, we need to integrate the extracted knowledge to enable quality-optimized MCS. For example, in both the participant selection and ground truth inference phase, we should assign a higher priority to the participants who are more willing to accept tasks, more reliable, and with better spatial-temporal coverage.

2) Sensing cost control. The process of participation in MCS campaigns leads to costs such as energy consumption, data transferring fee, and attention occupation for the participants. To compensate these, the task organizer needs to pay incentive rewards to motivate a large number of participants. The extracted knowledge in the learning phase can help us reduce cost. For example, with spatial correlation in mind, we can select a subset of more informative areas (i.e., having the highest information gain in terms of deducing the sensing data in other unselected areas), and then deduce the sensing data in unselected ones.

The above process is iterative in nature, in which the behavior data about participants and sensing data of MCS tasks are collected continuously to update the multi-aspect knowledge. Then, the updated knowledge will be further used in the MCS process.

4 Learning and Optimization Techniques

In this section, we present the existing approaches for optimizing MCS through learning techniques and summarize their contributions. We divide the state-of-the-art studies into the following groups: (1) Participant-Oriented Learning; based on the participants’ profile, historical mobility traces, and participation records, we can learn and predict participants’ behavior in MCS, which can be leveraged to recruit and select more beneficial participants, or assist them to better complete sensing tasks. (2) Task-Oriented Learning; the objective of this group of research works is to mine the data correlation in MCS tasks, and then exploit this to reduce the sensing cost or improve sensing quality.

4.1 Participant-Oriented Learning

A number of research studies use a data-driven approach to learn participants’ behavioral patterns and exploit it in assigning tasks to more preferred participants. As a given study may involve several aspects, Table 1 summarizes this set of works in terms of the learned knowledge.

1) Willingness. Most of existing works (such as [29], [30], [31], [32], [33]) assume that once a participant is assigned with a task, she/he will accept and complete it. However, this is not true in real-world settings, as participants may reject the task due to several reasons. Neglecting this issue has negative impact on the performance of MCS applications. To address this problem, the authors in [22] conducted a 4-week extensive smartphone user study to explore what are the factors influencing participants’ participation willingness. Their findings show that data was shared significantly more when anonymously collected, and that the data type is also an important factor. The authors in [28] carried out a study in Chicago to explore the geographic factors influencing the participation willingness, and quantitative modeling shows that travel distance to the location of the task and the socioeconomic status (SES) (i.e. a measure of ones’ economic and social position based on income, education, and occupation) of the task area are important factors. These results indicate that low-SES areas are currently less able to take advantage of the benefits of MCS. In a mobile crowdsourcing framework named GP-Selector [23], the authors developed a multi-classifier based approach to infer if a participant will accept an MCS task or not, where the influencing features are the incentive reward, domain interest, task workload, and privacy concern. In the focused scenario of [24], the authors assume that the participants decide whether to accept the task based on the incentive reward and movement distance. They developed a SVM-based method to learn the relationship between task acceptance rate and these two factors, and then utilize it to design better pricing mechanisms, with the objective of reducing sensing cost while ensuring task completion. In [25], the authors have taken participants’ rejection into consideration and tried to maximize the overall acceptance in order to improve the system throughput. Lastly, whether a person can be interrupted in a given situation also influences the likelihood of willingness, as explored in [68], especially if the contribution relies on manual reporting.

2) Mobility Pattern. Contrary to generic online crowdsourcing, MCS requires the participants’ physical movement
to specific locations for task completion. Thus, the mobility pattern of the participants significantly affects the task assignment process. In [26], [27], based on a real-world deployed MCS platform in campus, authors provided an analysis for the efficiency of recommending tasks based on predicted movement patterns of individual workers. With the goal of optimizing the spatial-temporal coverage in budget-constrained MCS, a group of works such as [29], [30], [31], [32], [33] studied the optimal task allocation based on the learning participants’ mobility pattern from the previous trajectories. For example, [29], [31], [32], [33] assumed that the number of calls in each spatial-temporal cell follows a Poisson distribution, and they calculate the probability of participants’ presence in each spatial-temporal cell based on historical trajectories. The authors in [30] adopted a location probability transition approach (i.e., calculating the transition probability between two locations) to accomplish mobility learning and prediction.

3) Sensing Context. Sensing context (e.g., the participants’ motion and the position of the mobile device) has a significant impact on the sensing data quality for certain types of MCS tasks. The authors in [34] trained a sensing data quality classifier, which extract the relation between context information (such as the participants’ motion) and sensing data quality, to estimate data quality in MCS. This classifier can be applied to guide user recruitment and task assignment in MCS.

4) Ability and Reputation. Learning participants’ abilities and reputations can help selecting more capable and reliable participants [35], [36], [37], [38], [39]. For instance, through an empirical study, [35] revealed that participants’ cognitive abilities correlate tightly with their crowdsourcing performance, where they built two models for crowdsourcing task performance prediction. In another example, [36] proposed a reputation-based system that employs the Gompertz function for learning the participants’ reputation score, and implement this idea in the scenario of a crowd noise level monitoring application. Though with different definitions of reputation metrics, they learn the reputation scores in either of the two categories: 1) statistical reputation scores that are computed based on the comparison between reported data and estimated the ground truth, 2) vote-based reputation scores by the participants of MCS.

4.2 Task-Oriented Learning Approaches

Learning techniques also can be used to extract knowledge from the perspective of the tasks. Here we will present how the learning approach can optimize MCS in sensing data correlation learning and sensing data aggregation.

4.2.1 Sensing Data Correlation Learning

Learning and exploiting sensing data correlation is an important technique to optimize the MCS process. It is based on the notion that, typically, there is a correlation among diverse sensing targets in the real world, and we can use this to address the sensing data redundancy and sparsity issues in MCS. By appropriately using data correlation, we can require the participants to collect only a relatively small number of data samples and deduce more information, thus the cost of MCS is significantly reduced.

In recent years, a number of studies in MCS focus on these aspects. Both [40] and [41] investigated a traffic status monitoring task, in which they use the correlation between the traveling speed on different roads sections to maximize the sensing accuracy with a fixed number of crowd sensors. The authors in [42], [43], [44], [45] utilized the spatial-temporal correlation of environmental sensing data (e.g., temperature and air quality) to achieve an optimized tradeoff between sensing cost and quality, in which they use matrix completion technology to infer the missing sensing data. The study in [46] demonstrated the feasibility of applying compressive sensing to data domains like large-scale question-based user surveys. The approach proposed in [47] is the extension of [46], which considered the sensing data reliability in different subareas due to different sampling density. Both [48] and [49] built a dependency graph between different entities in the city (such as the availability of shops and gas stations) to increase fact-finding accuracy. Focusing on the scenario where MCS is utilized to collect training data of context-aware applications, [50] proposed an active learning framework for optimally budgeted MCS. The authors in [73] exploited the spatial-temporal correlation of users’ mobility to achieve the tradeoff between MCS task performance and privacy preserving objective.

Although the above literature is different in terms of data type and detailed algorithms, they also attempt to address one of the three important issues: 1) Informative Sampling: how to select the most informative data collections? 2) Missing Data Inference: how to infer the missing data from the obtained one? 3) Quality Estimation: how to estimate if the inference meets the accuracy requirement without ground-truth sensing data. The summary is in Table 2.

4.2.2 Sensing Results Aggregation

Different from the traditional wireless sensor network, MCS faces the challenge of unreliable data samples due to many reasons (e.g., uncertain sensing context and malicious participants). To achieve high-quality results, we need to collect sensing data from multiple participants for the same sensing target and infer the truth. This problem is similar to truth discovery, which has been studied extensively in the general crowdsourcing community. Specifically, there are two inputs, i.e., the task answers and the expertise of each participant. Recently, a survey has comprehensively summarized this topic [51], where most of the literature [52], [53] use voting-based strategies, such as majority voting, weighted voting, Bayesian voting, etc.

Different from general online crowdsourcing, the truth discovery problem in MCS is more complex because of the multi-modality nature and spatial-temporal features of the sensing data, and some participant-side factors (e.g., location privacy). Thus, the techniques that existing works adopted for truth discovery in MCS are different to some degree. A number of works [54], [55], [56], [57], [58] leveraged Expectation Maximization (EM) based algorithms to estimate the reliability of participants or mobile devices, which will be used as the weight to infer the ground truth of sensing data. Some other works [59], [60] have adopted unsupervised learning approaches, in which they employ an additional optimization objective to improve the EM-based
method. Recently, truth discovery concerning the privacy-preserving issue has been studied [61], which infers the missing data using matrix factorization techniques.

### 5 HOW TO CONDUCT EVALUATION

One important question about the research on learning-based MCS optimization is that: *Where can we get the training data, and how to evaluate the performance of a given approach?* We know that the ideal way is to obtain large-scale data about participants’ behavior and collected sensing data, based on which extensive evaluation can be conducted. However, it is difficult to conduct such a large-scale and real-world evaluation as platforms, such as Amazon Mechanical Turk and WAZE, are not willing to open their data due to commercial reasons. Thus, researchers adopt alternative ways to demonstrate the feasibility of their proposed approach. In this section, we summarize different methodologies, which we hope can inspire and support the evaluation of future research efforts.

By summarizing the existing work, the evaluation methodology can be divided into the following three categories.

1. **Small-scale real-world evaluation.** A group of studies develops their own testbed to collect relevant data for evaluation. For example, the authors in [26], [27] build campus-scale MCS platforms as the research testbeds, in which 80 real users are recruited to complete several types of MCS tasks within a 4-week period. Similar platforms such as gMission and ChinaCrowds are developed and utilized in studies such as [25], [56], [69], [70].

2. **Open dataset based evaluation.** Another group of research works evaluates their solutions based on an open dataset (such as D4D¹, Gowalla²). For example, [29], [31], [32], [33], [71] evaluate a mobility pattern learning algorithm and task assignment approach based on open data containing the mobility trace of a large number of participants (e.g., calling trace and check-in data in a social network). Furthermore, [48], [49] evaluate their dependency analysis approach with a real-world dataset about the availability of groceries, pharmacies, and gas stations during Hurricane Sandy. The authors in [42], [43] evaluate their missing data inference algorithms based on a campus-scale open dataset for temperature and air quality measures.

3) **Simulation-based evaluation.** Another alternative way is to develop a simulator, in which the agents (both the participants and task organizers) are simulated according to pre-defined rules. Then, we can use the simulated data generated by the agents to perform the evaluation. A significant number of studies adopt the simulation-based approach to evaluate their learning-based MCS optimization approaches [23], [25], [27], [29], [31], [32]. We also note that several papers published in top venues choose to conduct an evaluation of both the real-world and simulated data. This is because real-world data is always better, but they often constitute isolated points in a large space. The simulation, in contrast, can extensively test the performance under various settings. Conducting the experiments based on both these two types of data can make the research work more solid.

Actually, we believe that a promising method should be the combination of both real-world and simulative evaluation. For example, we can collect small-scale and real-world data to generate some key parameters, and use these parameters to enable a large-scale simulation. For example, in [66], the authors learn the distribution of the parameters about the participants’ preferences in completing MCS tasks using real-world data from 80 participants during 4 weeks. Then, they further evaluate the proposed algorithm by a simulation study, in which the parameters are generated based on the pre-learned distribution.

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### TABLE 1: Learning participant-side factors to optimize MCS: a summary

<table>
<thead>
<tr>
<th>References</th>
<th>Willingness</th>
<th>Mobility</th>
<th>Sensing context</th>
<th>Ability</th>
<th>Reputation</th>
</tr>
</thead>
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<tr>
<td>[22]</td>
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<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>[23]</td>
<td>Yes</td>
<td></td>
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<td></td>
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<tr>
<td>[24]</td>
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<td></td>
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<tr>
<td>[28]</td>
<td>Yes</td>
<td></td>
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<tr>
<td>[29], [30], [31], [32], [33]</td>
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<td></td>
<td></td>
<td>Yes</td>
<td></td>
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<tr>
<td>[34]</td>
<td>Yes</td>
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<td></td>
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<tr>
<td>[35]</td>
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<td></td>
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<tr>
<td>[36], [37], [38], [39]</td>
<td>Yes</td>
<td></td>
<td></td>
<td>Yes</td>
<td></td>
</tr>
</tbody>
</table>

### TABLE 2: A summary of studies to optimize MCS through the learning of the data correlation

<table>
<thead>
<tr>
<th>Literatures</th>
<th>Data Type</th>
<th>Informative Sampling</th>
<th>Missing Data Inference</th>
<th>Quality Estimation</th>
</tr>
</thead>
<tbody>
<tr>
<td>[40]</td>
<td>Traffic speed</td>
<td>Heuristic greedy</td>
<td>Markov random field</td>
<td>Not addressed</td>
</tr>
<tr>
<td>[41]</td>
<td>Traffic speed</td>
<td>Not addressed</td>
<td>Matrix completion</td>
<td>Not addressed</td>
</tr>
<tr>
<td>[42], [43]</td>
<td>Temperature, air quality</td>
<td>The variance of different inference algorithm</td>
<td>Matrix completion</td>
<td>Leave-one-out estimation</td>
</tr>
<tr>
<td>[44]</td>
<td>Air quality</td>
<td>Not addressed</td>
<td>Matrix completion</td>
<td>Not addressed</td>
</tr>
<tr>
<td>[45]</td>
<td>Temperature, air quality, traffic speed</td>
<td>The variance of different inference algorithm</td>
<td>Matrix completion</td>
<td>Leave-one-out estimation</td>
</tr>
<tr>
<td>[46]</td>
<td>Question-based user surveys</td>
<td>Compressive sensing</td>
<td>Matrix completion</td>
<td>Not addressed</td>
</tr>
<tr>
<td>[48], [49]</td>
<td>Availability of urban entities</td>
<td>Not addressed</td>
<td>Bayesian Network</td>
<td>Not addressed</td>
</tr>
<tr>
<td>[50]</td>
<td>Labels and training data for activity recognition apps</td>
<td>Active Learning</td>
<td>Not addressed</td>
<td>Not addressed</td>
</tr>
</tbody>
</table>
opportunities of learning-based MCS optimization, which

In this section, we highlight the research gaps and future
tasks until the total budget runs out.

final output (e.g., the city-scale air quality sensing map).

the application [42], [43], [45]. If yes, it will generate the

to access if the current results meet the requirement of

estimation method (e.g., leave-one-out) will be executed

[55], [56], [57], [58], to improve its quality. Then, a quality

data inference [42], [43], [44], [45] and truth discovery [54],

reports and will use learning techniques, such as missing

data for the assigned tasks. The server side receives the

of the selected participants will accept and report sensing

and more informative coverage in terms of mobility, and

higher likelihood to accept the tasks, who can obtain wider

form may prefer to select those participants who have a

output might be the classification model for predicting

willingness [23], [24], [25], location [29], [30], [31], [32], [33],
sensing context [34], ability and reputation [35], [36], [37],
[38], [39], etc. Here we should also note that the participant-
side classification models and predictors should also be re-

trained with updates in training data.

In the online phase, the MCS applications or platforms
select participants and assign tasks based on the utility
calculation, which will use the predicted participant-side
factors. Intuitively, through the utility calculation, the plat-
form may prefer to select those participants who have a
higher likelihood to accept the tasks, who can obtain wider
and more informative coverage in terms of mobility, and
who are more reliable or capable of completing tasks. Some
of the selected participants will accept and report sensing
data for the assigned tasks. The server side receives the
reports and will use learning techniques, such as missing
data inference [42], [43], [44], [45] and truth discovery [54],
[55], [56], [57], [58], to improve its quality. Then, a quality
estimation method (e.g., leave-one-out) will be executed
to access if the current results meet the requirement of
the application [42], [43], [45]. If yes, it will generate the
final output (e.g., the city-scale air quality sensing map).
Otherwise, it will iteratively select participants and assign
tasks until the total budget runs out.

7 Future Research Opportunities

In this section, we highlight the research gaps and future
opportunities of learning-based MCS optimization, which
may lead to novel solutions in this increasingly important field.

7.1 A Unified Middleware Framework

Each of the existing works tackles one specific aspect of
the learning-assisted MCS optimization. To develop a real-
world MCS application or system, we need to integrate
different techniques to form a complete optimizing solution.
In Section 6, we highlight the relationship between different
techniques and present a preliminary discussion about how
they may be combined to optimize the MCS process col-
laboratively. Thus, we argue that it is a promising research
direction to study a unified learning-assisted MCS optimiza-
tion framework by: 1) integrating different single techniques
into the framework, and 2) exploring if we can use one to
augment the others. Here, as there are multiple techniques
that can be used to implement a certain component, we need
to figure out what is the best combination in terms of the
performance. For example, after obtaining the reports from
different participants, the server may need to use missing
data inference techniques to infer the data of one sensing
subarea from the other (we refer this as “inter-subarea
inference” in this paper). In the meantime, it also needs to
discover the truth from multiple reports in the same subarea
(we refer this as “intra-subarea inference” in this paper). For
both inter-subarea and intra-subarea inferences, there are
multiple detailed algorithms, then the challenge is to obtain
the optimal combination and execution sequence. Besides,
the learning-assisted MCS optimization is a common func-
tionality across multiple applications and it is technically
challenging for app developers. Thus, it is preferred that we
develop a middleware framework with several application
interfaces (API). Through these APIs and guidance about
how these API should be combined, the technical threshold
becomes lower and the developers can build their own app
or system in a faster manner.

7.2 Leveraging Sensing Context

Mobile phones have an increasing number of sensors that
can be leveraged to determine the participants’ current sens-
ning context. This includes not only hardware sensors (e.g.,
accelerometer, gyroscope, screen state), but also software
sensors (e.g., notifications, application usage and selections).
However, as shown in this survey there are not that many
examples of sensing context being effectively used in MCS,
particularly with regards to software sensors. Given the
availability of this rich contextual information, there is a sig-
nificant research opportunity to develop improved learning-
asstisted mechanisms for MCS optimization by leveraging
this data. Hence, it is important to empirically determine
the effect of different contextual factors on the likelihood of
a participant completing an MCS task as well as their impact
on data quality. For instance, information on how long ago
a participant last used their device can provide hints on when
to deliver MCS tasks. Session duration can also influence
one’s participation [72]. In another example, by detecting
instances where a participant is bored it is then possible to
take advantage of their contextual cognitive surplus [65].
7.3 Knowledge Transferring

Existing works mainly extract knowledge from an individual participant or task, which is an initial step to integrate learning techniques into MCS optimization. Nevertheless, this may turn out to be impractical in some real-world settings. For example, data sparsity can be a challenging issue. For new participants and tasks or due to the reason of privacy preservation, some types of historical data are not always available. In this case, studying the similarity among different participants/tasks and leveraging it in MCS optimization to tackle the data sparsity issue can be a potential research opportunity. For example, we can infer a participant’s willingness and reliability from other similar ones. Alternatively, we can deduce the participant’s mobility pattern in platform A through his/her traces on other platforms (such as B, C and D). It is also interesting to compare the behavioral pattern of the same set of participants on different sensing tasks, or different clusters of participants on the same sensing task, which may reveal beneficial insights about how we should design an MCS system.

7.4 Task Routing and Assignment

Currently, most MCS systems rely on a central authority to coordinate the task assignment process, not taking into account participants’ interest and skills. There is a significant research opportunity to develop and evaluate simple and robust mechanisms to determine a participant’s aptitude to complete tasks before they are assigned a sizable amount of work. For instance, a number of qualification tasks could be deployed to verify the aptitude of a participant to complete tasks of the same type. This way, the amount of data collection and analysis effort could be substantially reduced.

8 Conclusion

In this article, we presented a survey of learning-assisted MCS optimization. Specifically, we summarized state-of-the-art research in the perspective of participant and task, and presented different learning and optimization approach together with their evaluation. Furthermore, we discussed how different individual techniques can be integrated to optimize MCS together. In the end, we highlight the gaps in this area and propose future research opportunities.

REFERENCES


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